

CLAIMS

1. A surgical holder comprising a grasping member for grasping a tissue, a manipulation member for manipulating the grasping member, and a connection portion with one end connected to the manipulation member, wherein:

the grasping member includes a first grasping plate, and a second grasping plate provided so as to oppose the first grasping plate in a movable manner so that they are able to become closer to each other or more distanced from each other;

a first grasping portion which can grasp a part of a tissue between the first grasping plate and the second grasping plate, and an opening which can expose another part of the tissue when the part of the tissue is grasped by the first grasping portion are provided in one end portion of the grasping member; and

a second grasping portion which can form a tissue grasping space between the first grasping plate and the second grasping plate is provided in another end portion of the grasping member.

2. A surgical holder according to claim 1, wherein a tissue protection material is attached to an opposing surface of the first grasping plate and/or the second grasping plate.

3. A surgical holder according to claim 2, wherein the tissue protection material is permeated with medicines.

4. A surgical holder comprising a grasping member for grasping a tissue, a manipulation member for manipulating the grasping member, and a connection

portion with one end connected to the manipulation member and the other end provided with a fixing tool, wherein:

the grasping member includes a first grasping plate, and a second grasping plate provided so as to oppose the first grasping plate in a movable manner so that they are able to become closer to each other or more distanced from each other;

the first grasping plate includes a retaining portion having the opening and a supporting portion having a recessed portion;

the second grasping plate includes a covering portion formed so as to cover an entire surface or a part of the opening of the first grasping plate, a non-covering portion which does not cover the first grasping plate, and a fixing portion having a curved portion which is provided so as to oppose the recessed portion of the first grasping plate and can form a tissue grasping space.

5. A surgical holder comprising a grasping member for grasping a tissue, a manipulation member for manipulating the grasping member, and a connection portion with one end connected to the manipulation member and the other end provided with a fixing tool, wherein:

the grasping member includes a first grasping plate, and a second grasping plate provided so as to oppose the first grasping plate in a movable manner so that they are able to become closer to each other or more distanced from each other;

the grasping member is formed into a rectangular shape with the manipulation member elongated from a side thereof;

a first grasping portion which can grasp a part of a tissue between the first grasping plate and the second grasping plate, and an opening which is provided in

the vicinity of the first grasping portion and exposes another part of the tissue are provided in one end portion of the grasping member; and

a second grasping portion which can form a tissue grasping space between the first grasping plate and the second grasping plate is provided in another end portion of the grasping member.

6. A surgical holder comprising a grasping member for grasping a tissue, a manipulation member for manipulating the grasping member, and a wiring portion connected to the manipulation member, wherein:

the grasping member includes a first grasping plate and a second grasping plate;

the first grasping plate includes a retaining portion having an opening of a U-shape or substantially a U-shape, and a supporting portion having a recessed portion; and

the second grasping plate includes a covering portion formed to cover an entire surface or a part of the opening of the first grasping plate, a non-covering portion which does not cover the first grasping plate, and a fixing portion having a curved portion.

7. A surgical holder according to claim 6, wherein the tissue to be grasped is a tubular tissue with a surrounding tissue, and the surrounding tissue is grasped by a part which defines the shape of the opening of the first grasping plate and the covering portion of the second grasping plate.

8. A surgical holder according to claim 6, wherein the tissue to be grasped is a tubular tissue, and the tubular tissue is grasped by a tissue grasping space formed by the recessed portion of the first grasping plate and the curved portion of the second grasping plate.
9. A surgical holder according to claim 6, wherein the tissue to be grasped is a tubular tissue, and the tubular tissue is grasped with one point of the tubular tissue being grasped by the retaining portion of the first grasping plate and the covering portion of the second grasping plate, and another point being grasped by a tissue grasping space formed by the recessed portion of the first grasping plate and the curved portion of the second grasping plate.
10. A surgical holder according to claim 6, wherein the tissue to be grasped is a tubular tissue, and an end portion of the retaining portion which defines the opening of the first grasping plate is inserted into a tube of the tubular tissue to grasp the tubular tissue.
11. A surgical holder according to claim 6, wherein the tissue to be grasped is a tubular tissue (A), and, (i) with one point of the tubular tissue (A) grasped by the retaining portion of the first grasping plate and the covering portion of the second grasping plate and another point of the tubular tissue (A) grasped by the tissue grasping space formed by the recessed portion of the first grasping plate and the curved portion of the second grasping plate, anastomosis manipulation between a cut portion of the tubular tissue (A) and a cut portion of a tubular tissue (B) positioned on the supporting portion is performed, and then, (ii) with the tubular

tissue (A) grasped by the tissue grasping space formed by the recessed portion of the first grasping plate and the curved portion of the second grasping plate, anastomosis manipulation between a cut portion of the tubular tissue (A) and a cut portion of the tubular tissue (C) positioned on the supporting portion is performed.